



PIC18 Timer Programming

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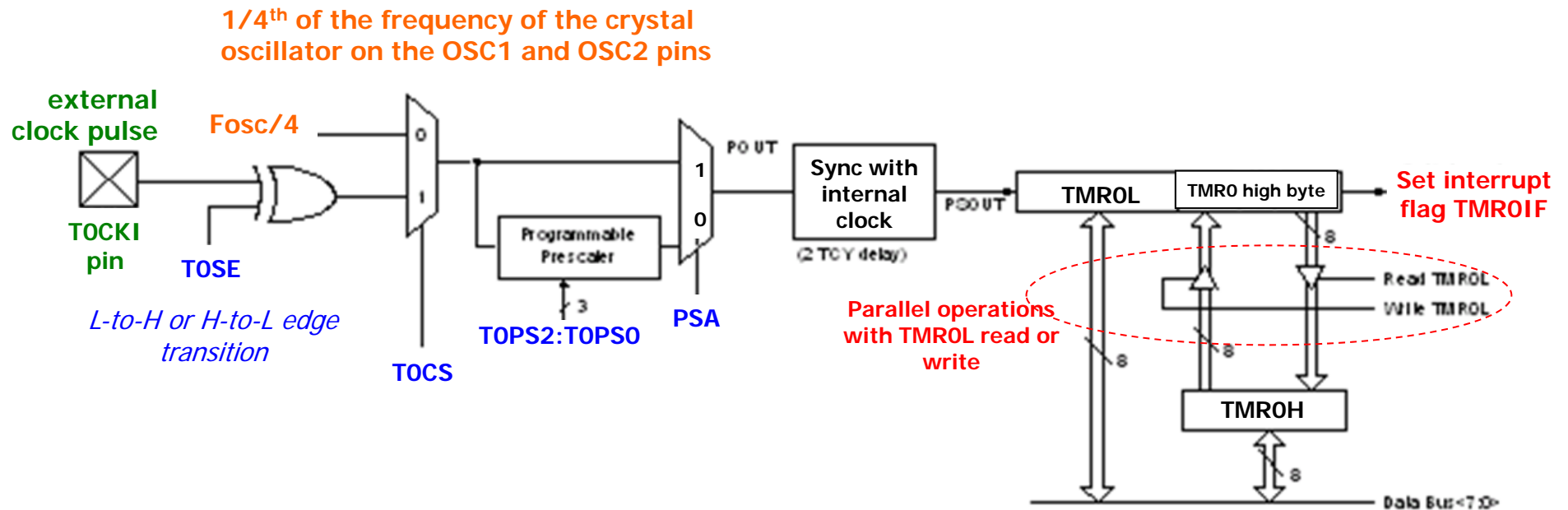
Objectives

- Introduce PIC18 timers
 - Timer 0, Timer 1, Timer 2, Timer 3
- Generate a time delay using a timer
- Generate a square wave using a timer
- Count external pulses using a timer
- Use C as well as assembly in timer programming

Functions of PIC18 timer

- Generate a time delay (計時器)
 - Use internal clock pulse, $F_{osc}/4$
- As a counter to count events happening outside the microcontroller (計數器)
 - Use external clock pulse

Timer0 16-bit block diagram



- Should load TMROH first, and then TMROL

(Figure 9-5)

Registers of the timer

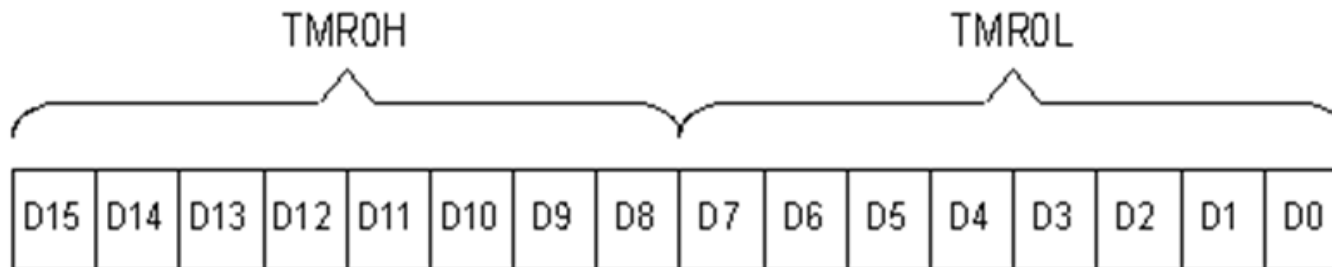
F80h	PORTA	FA0h	PIE2	FC0h	----	FE0h	BSR
F81h	PORTB	FA1h	PIR2	FC1h	ADCON1	FE1h	FSR1L
F82h	PORTC	FA2h	IPR2	FC2h	ADCON0	FE2h	FSR1H
F83h	PORTD	FA3h	----	FC3h	ADRESL	FE3h	PLUSW1 *
F84h	PORTE	FA4h	----	FC4h	ADRESH	FE4h	PREINC1 *
F85h	----	FA5h	----	FC5h	SSPCON2	FE5h	POSTDEC1 *
F86h	----	FA6h	----	FC6h	SSPCON1	FE6h	POSTINC1 *
F87h	----	FA7h	----	FC7h	SSPSTAT	FE7h	INDF1 *
F88h	----	FA8h	----	FC8h	SSPADD	FE8h	WREG
F89h	LATA	FA9h	----	FC9h	SSPBUF	FE9h	FSROL
F8Ah	LATB	FAAh	----	FCAh	T2CON	FEAh	FSROH
F8Bh	LATC	FABh	RCSTA	FCBh	PR2	FEBh	PLUSW0 *
F8Ch	LATD	FACH	TXSTA	FCCh	TMR2	FECb	PREINC0 *
F8Dh	LATE	FADh	TXREG	FCDh	T1CON	FEDh	POSTDEC0 *
F8Eh	----	FAEh	RCREG	FCEh	TMR1L	FEEh	POSTINC0 *
F8Fh	----	FAFh	SPBRG	FCFh	TMR1H	FEFh	INDF0 *
F90h	----	FB0h	----	FD0h	RCON	FF0h	INTCON3
F91h	----	FB1h	T3CON	FD1h	WDTCON	FF1h	INTCON2
F92h	TRISA	FB2h	TMR3L	FD2h	LVDCON	FF2h	INTCON
F93h	TRISB	FB3h	TMR3H	FD3h	OSCCON	FF3h	PRODL
F94h	TRISC	FB4h	----	FD4h	----	FF4h	PRODH
F95h	TRISD	FB5h	----	FD5h	TOCON	FF5h	TABLAT
F96h	TRISE	FB6h	----	FD6h	TMR0L	FF6h	TBLPTRL
F97h	----	FB7h	----	FD7h	TMR0H	FF7h	TBLPTRH
F98h	----	FB8h	----	FD8h	STATUS	FF8h	TBLPTRU
F99h	----	FB9h	----	FD9h	FSR2L	FF9h	PCL
F9Ah	----	FBAh	CCP2CON	FDAh	FSR2H	FFAh	PCLATH
F9Bh	----	FBBh	CCPR2L	FDBh	PLUSW2 *	FFBh	PCLATU
F9Ch	----	FBCh	CCPR2H	FDCb	PREINC2 *	FFCh	STKPTR
F9Dh	PIE1	FBDh	CCP1CON	FDDh	POSTDEC2 *	FFDh	TOSL
F9Eh	PIR1	FBEh	CCPR1L	FDEh	POSTINC2 *	FFEh	TOSH
F9Fh	IPR1	FBFh	CCPR1H	FDfh	INDF2 *	FFFh	TOSU

* - These are not physical registers.

Special function registers (SFRs)

Timer0 registers

- Timer0 can be used as an 8-bit or 16-bit timer
- Can be accessed like any SFRs
 - MOVWF TMR0L
 - MOVFF TMR0H, PORTC



(Figure 9-1)

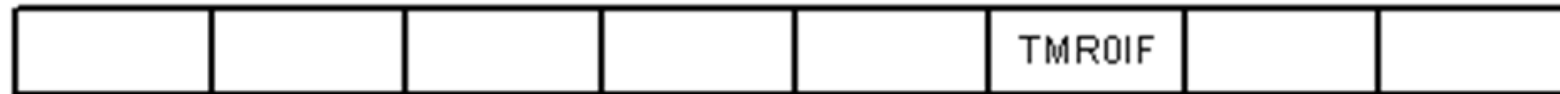
T0CON (Timer0 control) register

- Set various timer operation mode

TMR0ON	T08BIT	T0CS	T0SE	PSA	T0PS2	T0PS1	T0PS0
TMR0ON	D7	Timer0 ON and OFF control bit 1 = Enable (start) Timer0 0 = Stop Timer0					
T08BIT	D6	Timer0 8-bit/16-bit selector bit 1 = Timer0 is configured as an 8-bit timer/counter. 0 = Timer0 is configured as a 16-bit timer/counter.					
T0CS	D5	Timer0 clock source select bit 1 = External clock from RA4/T0CKI pin 0 = Internal clock ($F_{osc}/4$ from XTAL oscillator)					
T0SE	D4	Timer0 source edge select bit 1 = Increment on H-to-L transition on T0CKI pin 0 = Increment on L-to-H transition on T0CKI pin					
PSA	D3	Timer0 prescaler assignment bit 1 = Timer0 clock input bypasses prescaler. 0 = Timer0 clock input comes from prescaler output.					
T0PS2:T0PS0	D2:D1:D0	Timer0 prescaler selector					
	0 0 0	= 1:2 Prescale value ($F_{osc} / 4 / 2$)					
	0 0 1	= 1:4 Prescale value ($F_{osc} / 4 / 4$)					
	0 1 0	= 1:8 Prescale value ($F_{osc} / 4 / 8$)					
	0 1 1	= 1:16 Prescale value ($F_{osc} / 4 / 16$)					
	1 0 0	= 1:32 Prescale value ($F_{osc} / 4 / 32$)					
	1 0 1	= 1:64 Prescale value ($F_{osc} / 4 / 64$)					
	1 1 0	= 1:128 Prescale value ($F_{osc} / 4 / 128$)					
	1 1 1	= 1:256 Prescale value ($F_{osc} / 4 / 256$)					

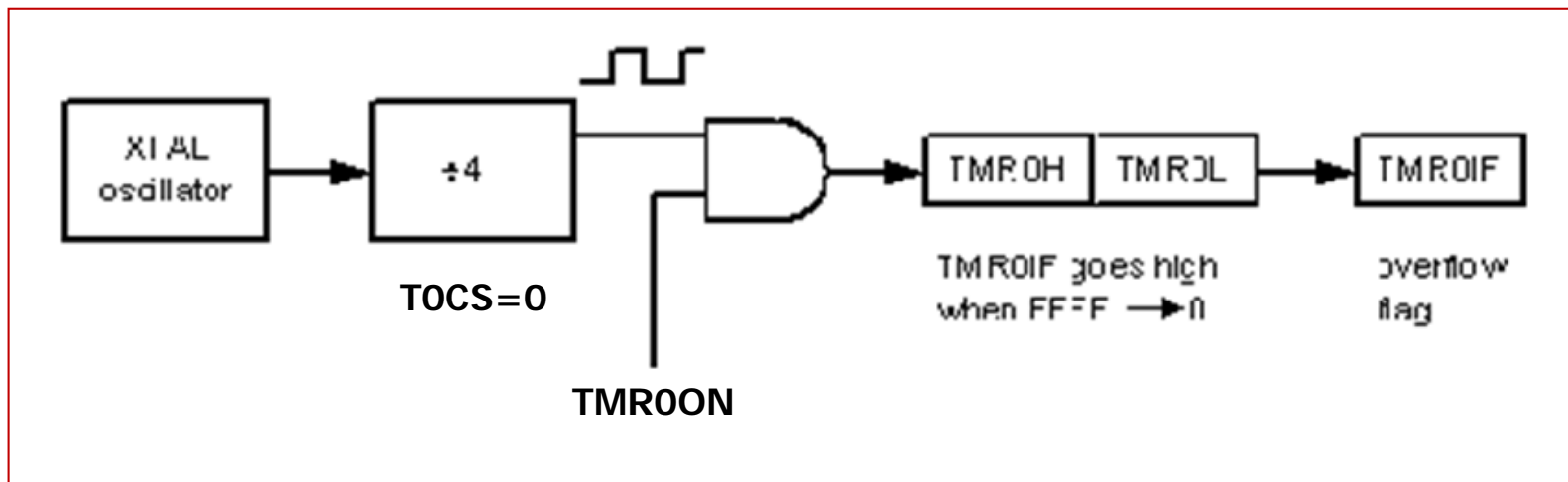
(Figure 9-2)

TMR0IF flag bit in INTCON (interrupt control register)

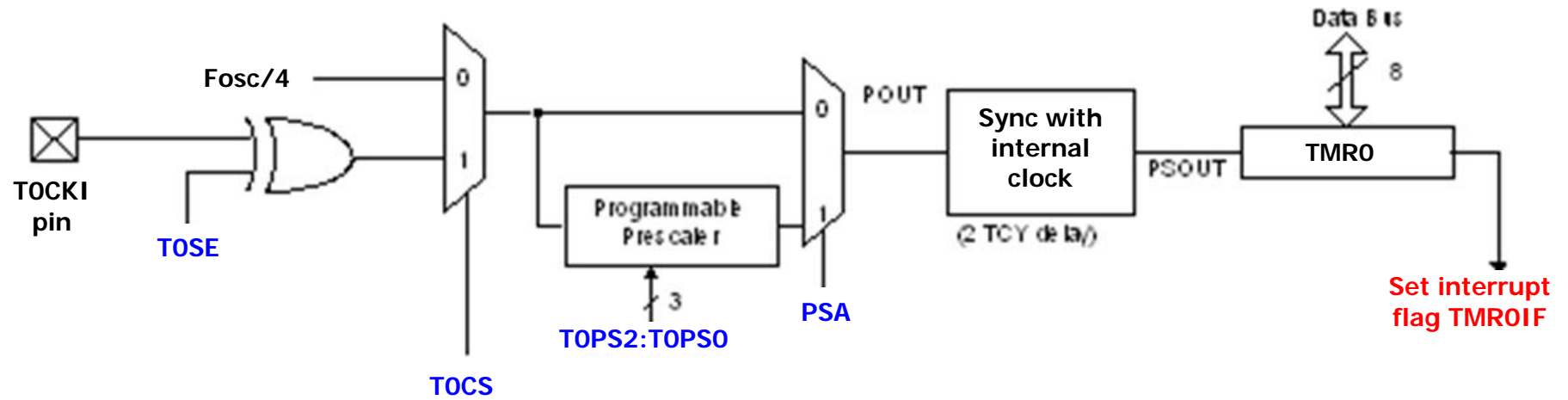


TMR0IF D2 Timer0 interrupt overflow flag bit
0 = Timer0 did not overflow.
1 = Timer0 has overflowed (FFFF to 0000, or FF to 00 in 8-bit mode).

The importance of TMR0IF: In 16-bit mode, when TMR0H:TMR0L overflows from FFFF to 0000 this flag is raised. In 8-bit, it is raised when the timer goes from FF to 00. We monitor this flag bit before we reload the TMR0H:TMR0L registers. (Figure 9-3,4)



8-bit mode programming of Timer0



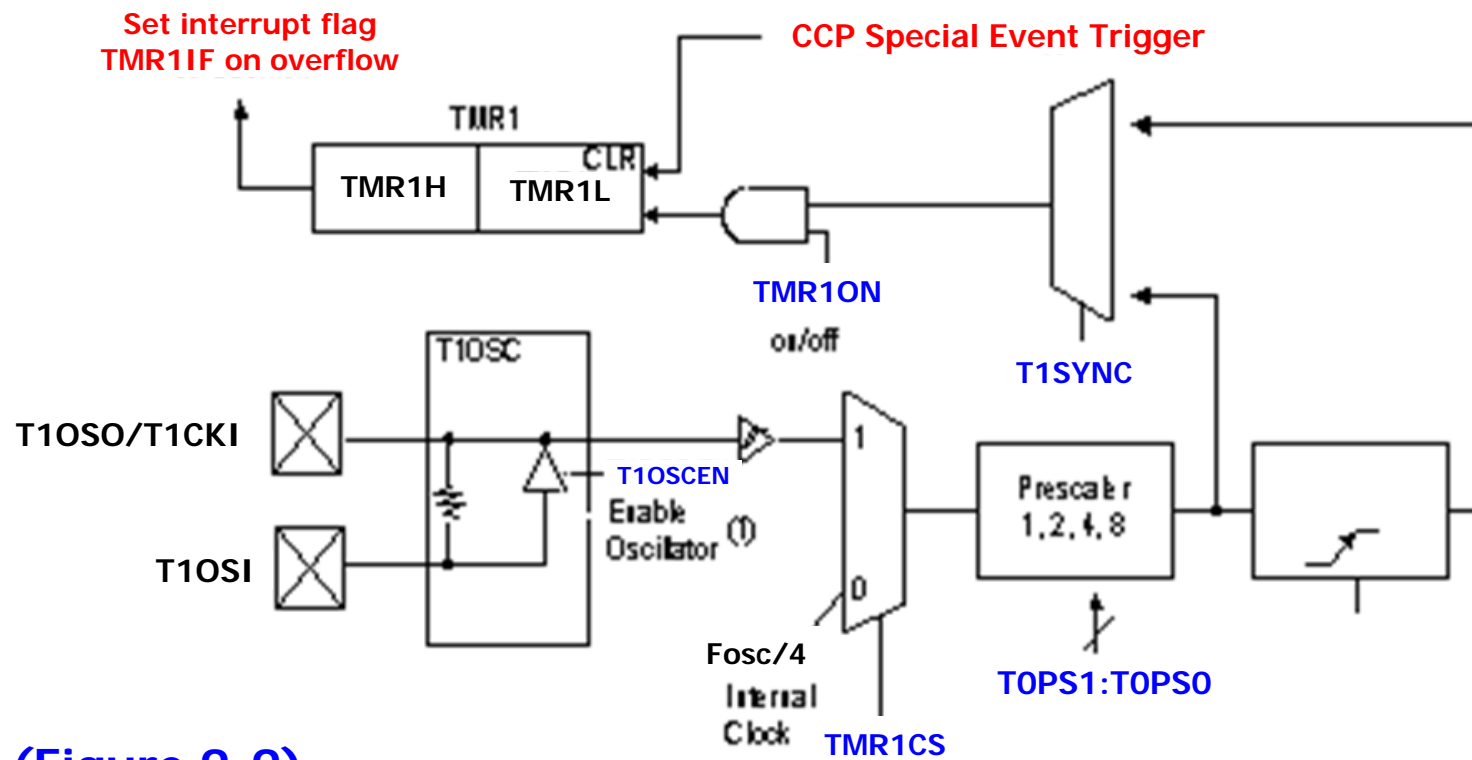
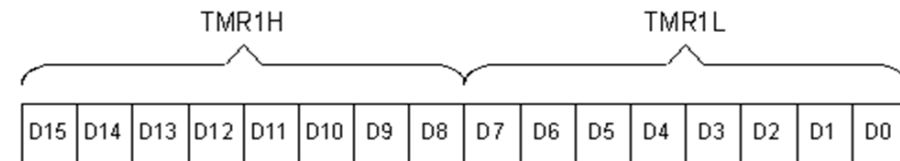
(Figure 9-7)

Examples using Timer 0

- Assembly programming
 - Find frequency of square wave using 16-bit timer (Example 9-7)
 - Find frequency of square wave using 8-bit timer (Example 9-19)
- C programming
 - Toggle RB5 every 50 ms using 16-bit timer (Example 9-29)
 - Generate 2-Hz square wave using 8-bit timer (Example 9-30)

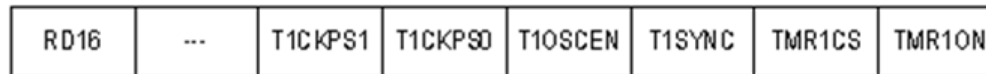
Timer1

- Only support 16-bit mode



(Figure 9-9)

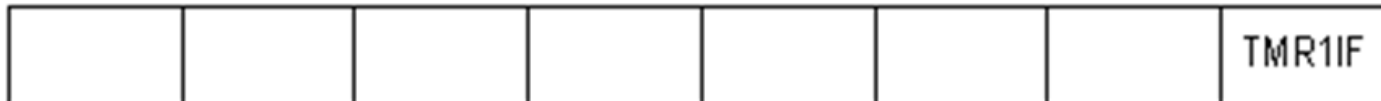
T1CON (Timer1 control) register



RD16	D7	16-bit read/write enable bit 1 = Timer1 16-bit is accessible in one 16-bit operation. 0 = Timer1 16-bit is accessible in two 8-bit operations.
	D6	Not used
T1CKPS2:T1CKPS0	D5 D4	Timer1 prescaler selector 0 0 = 1:1 Prescale value 0 1 = 1:2 Prescale value 1 0 = 1:4 Prescale value 1 1 = 1:8 Prescale value
T1OSCEN	D3	Timer1 oscillator enable bit 1 = Timer1 oscillator is enabled. 0 = Timer1 oscillator is shutoff
T1SYNC	D2	Timer1 synchronization (used only when TMR1CS = 1 for counter mode to synchronize external clock input) If TMR1CS = 0 this bit is not used.
TMR1CS	D1	Timer1 clock source select bit 1 = External clock from pin RC0/T1CKI 0 = Internal clock (Fosc/4 from XTAL)
TMR1ON	D0	Timer1 ON and OFF control bit 1 = Enable (start) Timer1 0 = Stop Timer1

(Figure 9-10)

PIR1 (interrupt control register 1)



TMR1IF D1 Timer1 Interrupt overflow flag bit
0 = Timer1 did not overflow.
1 = Timer1 has overflowed (FFFF to 0000).

The importance of TMR1IF: When TMR1H:TMR1L overflows from FFFF to 0000, this flag is raised. We monitor this flag bit before we reload the TMR1H:TMR1L registers.

(Figure 9-11)

Examples using Timer 1

- Generate a square wave using assembly (Example 9-21)
- Generate a square wave using C (Example 9-33)

Counter programming

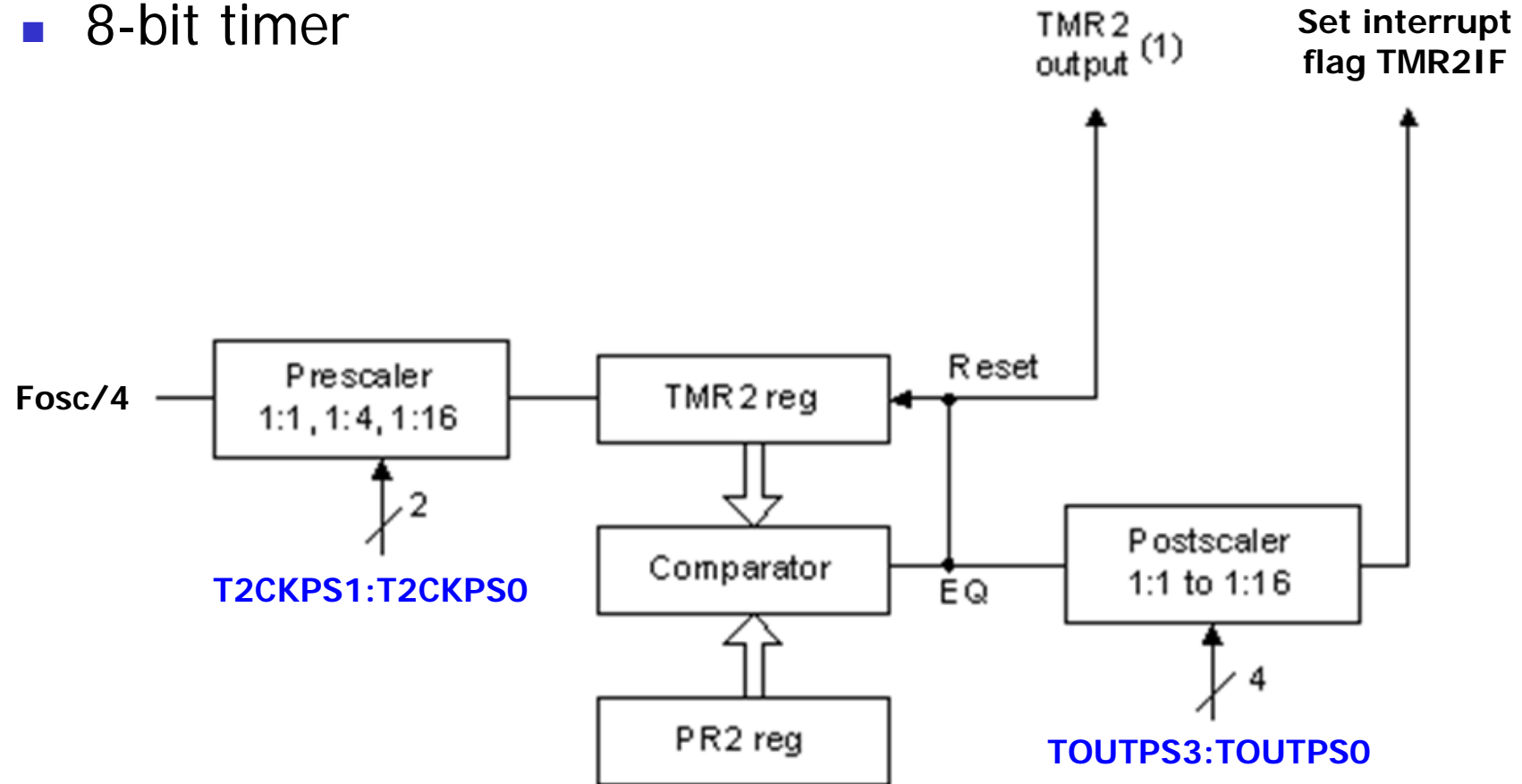
- Using Timer 0
 - Get pulses from T0CKI (Timer0 clock input): RA4 (PORTA.4)
 - Set T0CS (Timer0 clock source) in T0CON to 1
- Using Timer 1
 - External clock is fed into T1CKI pin
 - External clock source option (TMR1CS) is set to 1
 - Timer1 oscillator enable bit (T1OSCEN) is set to 1

Examples for counter programming

- Assembly programming
 - Count pulse using 8-bit Timer 0 (Example 9-26)
 - Count pulse using 16-bit Timer 1 (Example 9-27)
- C programming
 - Count pulse using 16-bit Timer 0 (Example 9-35)

Timer2 block diagram

- 8-bit timer



(Figure 9-12)

T2CON (Timer2 control) register



D7 Not used

TOUTPS3:TOUTPS0 D6–D3 Timer2 Output Postscale Select bits

00 0 0 = 1:1 Postscale value

00 0 1 = 1:2 Postscale value

00 1 0 = 1:3 Postscale value

00 1 1 = 1:4 Postscale value

11 1 0 = 1:15 Postscale value

11 1 1 = 1:16 Postscale value

TMR2ON D2 Timer2 ON and OFF Control bit

1 = Enable (Start) Timer2

0 = Stop Timer2

T2CKPS1:T2CKPS0 D1–D0 Timer2 Clock Prescale Select bits

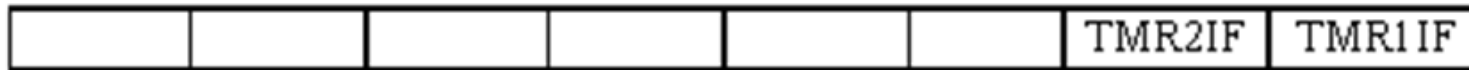
0 0 = Prescale is 1

0 1 = Prescale is 4

1 x = Prescale is 16

(Figure 9-13)

PIR1 (interrupt control register 1)



TMR2IF Timer2 Interrupt overflow flag bit
0 = TMR2 value is not equal to PR2 register.
1 = TMR2 value is equal to PR2 register.

(Figure 9-14)

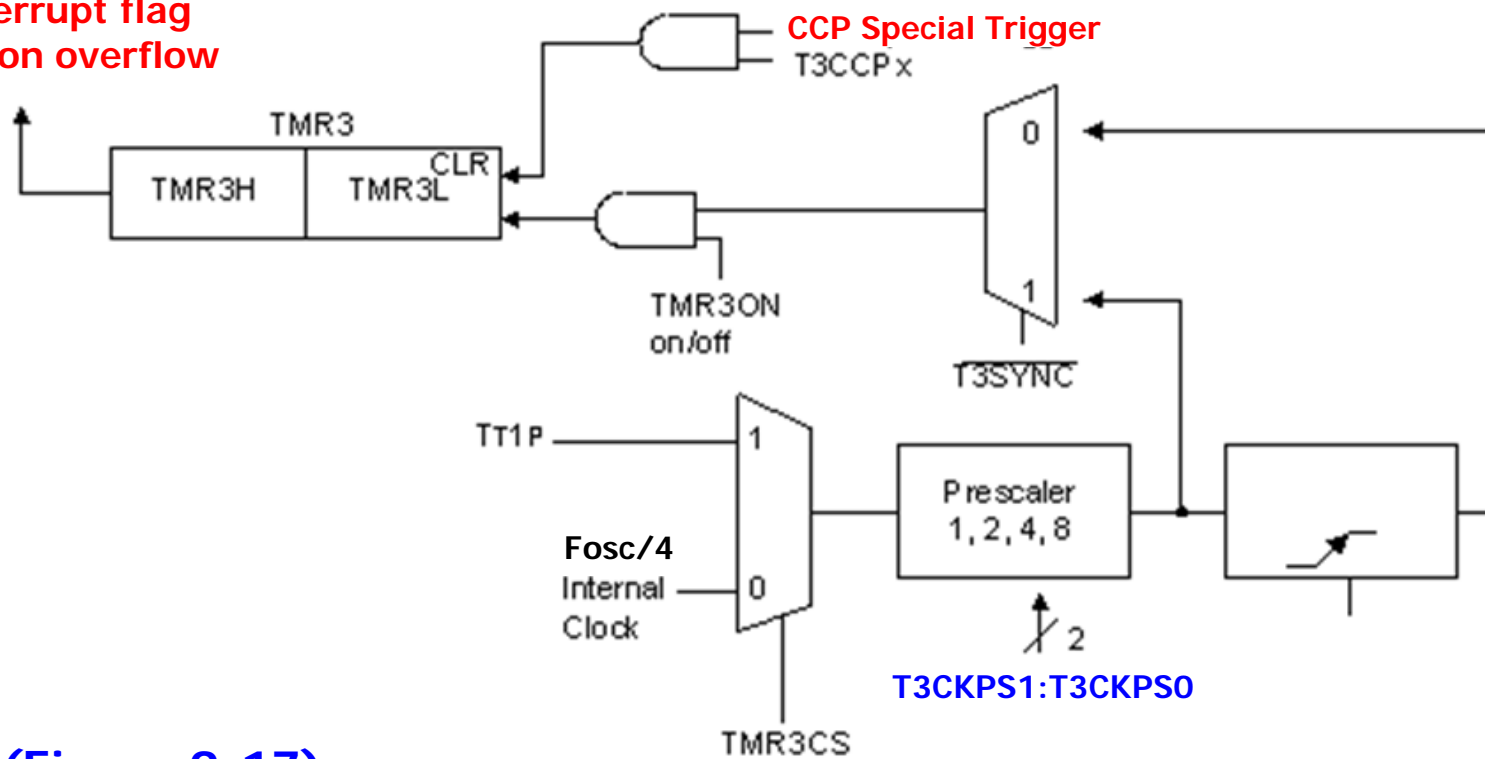
Examples using Timer 2

- Turn on after a period of time using assembly (Example 9-38)
- Generate a time delay using C (Example 9-41)

Timer3 block diagram

- 16-bit timer or counter

**Set interrupt flag
TMR3IF on overflow**



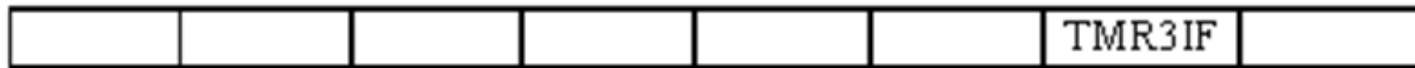
(Figure 9-17)

T3CON (Timer3 control) register

RD16	T3CCP2	T3CKPS1	T3CKPS0	T3CCP1	T3SYNC	TMR3CS	TMR3ON
RD16	D7	16-bit read/write enable bit 1 = Timer3 16-bit is accessible in one 16-bit operation. 0 = Timer3 16-bit is accessible in two 8-bit operations.					
T3CCP2:T3CCP1	D6 D3	Timer3 and Timer1 to CPPx Enable bits 0 0 = Timer1 is the clock source for compare/capture of the CCP module. 0 1 = Timer3 is the clock source for compare/capture of the CCP2. Timer1 is the clock source for compare/capture of the CCP1. 1 x = Timer3 is the clock source for compare/capture of the CCP module.					
T3CKPS1:T3CKPS0	D5 D4	Timer3 Input Clock Prescaler Selector 0 0 = 1:1 Prescale value 0 1 = 1:2 Prescale value 1 0 = 1:4 Prescale value 1 1 = 1:8 Prescale value					
T1SYNC	D2	Timer3 external clock input synchronization control bit Used only when TMR3CS = 1 and clock comes from an external source. If TMR3CS = 0, this bit is not used. 1 = Do not synchronize external clock input 0 = Synchronize external clock input					
TMR3CS	D1	Timer3 clock source select bit 1 = External clock from pin T1OSI or T1CKI 0 = Internal clock (Fosc/4)					
TMR3ON	D0	Timer3 On and Off control bit 1 = Enable (start) Timer1 0 = Stop Timer1					

(Figure 9-15)

PIR3 (interrupt control register 3)



TMR3IF Timer3 interrupt overflow flag bit
0 = Timer3 did not overflow.
1 = Timer3 has overflowed (FFFF to 0000).

The importance of TMR3IF: In 16-bit mode, when TMR3H:TMR3L overflows from FFFF to 0000, this flag is raised.

(Figure 9-16)

Generate a square wave of 50 Hz on the PORTB.5 bit if XTAL = 10 MHz

```

        BCF      TRISB, 5
        MOVLW   0x0          ; Timer3, 16-bit, internal clock, no prescale
        MOVWF  T3CON
HERE    MOVLW   0x9E          FFFFH – 9E58H + 1 = 25,000 clocks
        MOVWF  TMR3H        → time delay = 25,000 x 0.4 μs = 10 ms
        MOVLW  0x58          frequency = 1/(10 ms x 2) = 50 Hz
        MOVWF  TMR3L
        BCF    PIR2, TMR3IF ; clear Timer3 interrupt flag
        CALL   DELAY
        BTG   PORTB, RB5
        BRA   HERE

DELAY   BSF    T3CON, TMR3ON ; start Timer3
AGAIN  BTFSS  PIR2, TMR3IF ; monitor Timer3 interrupt flag
        BRA   AGAIN
        BCF   T3CON, TMR3ON ; stop Timer3
        RETURN
```

(Example 9-43)

Reference

- M.A. Mazidi, R.D. Mckinlay, D Causey, PIC Microcontroller and Embedded Systems Using Assembly and C for PIC18, Pearson Education Inc., 2008.
- Han-Way Huang, PIC Microcontroller: An Introduction to Software and Hardware Interfacing, Thomson Delmar Learning, 2005.