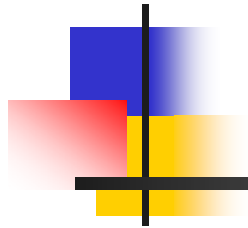


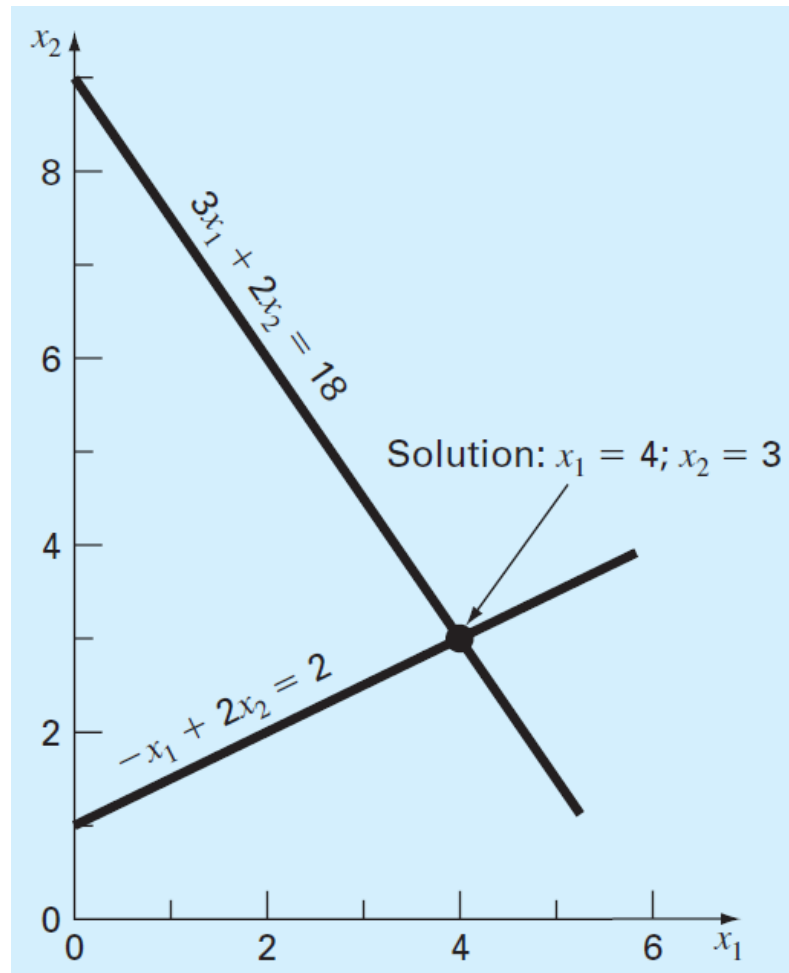
Gauss Elimination



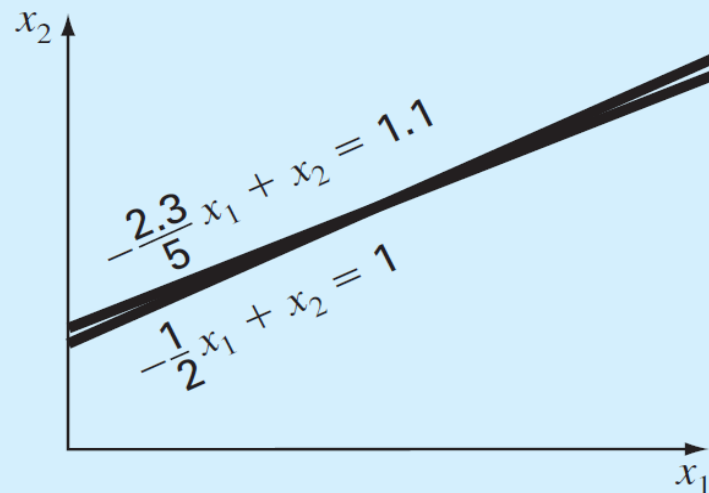
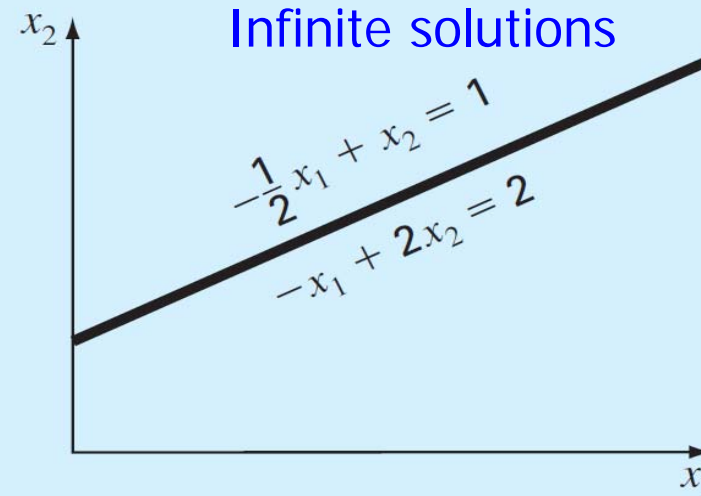
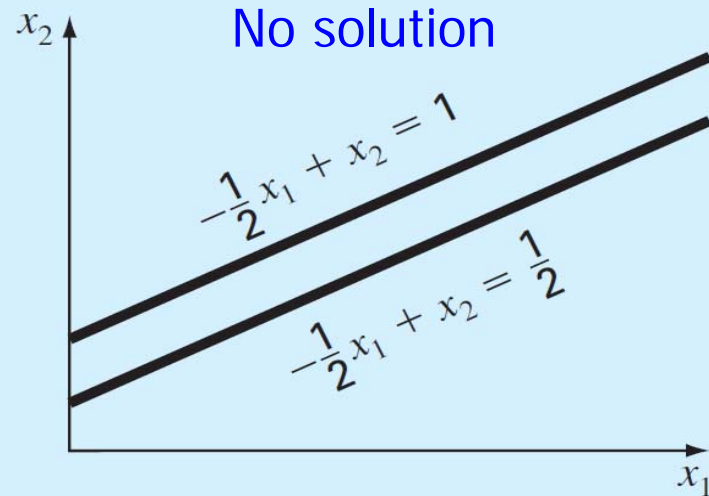
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Solving small numbers of equations by graphical method

- The location of the intercept provides a solution



Singular and ill-conditioned systems



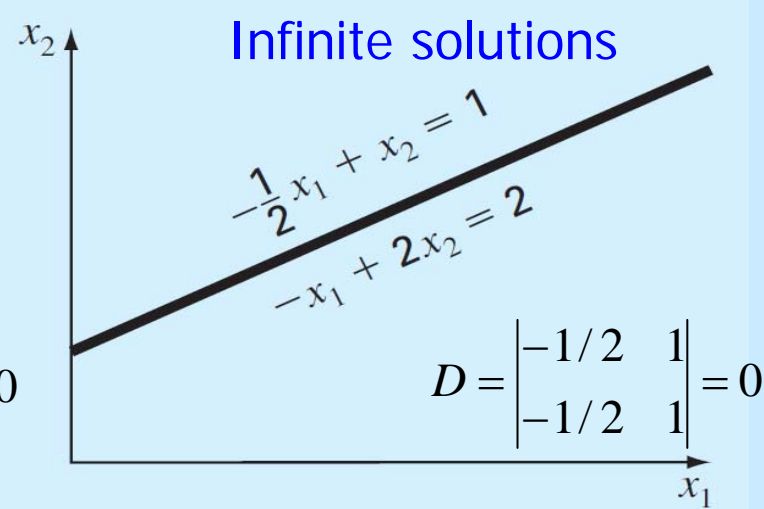
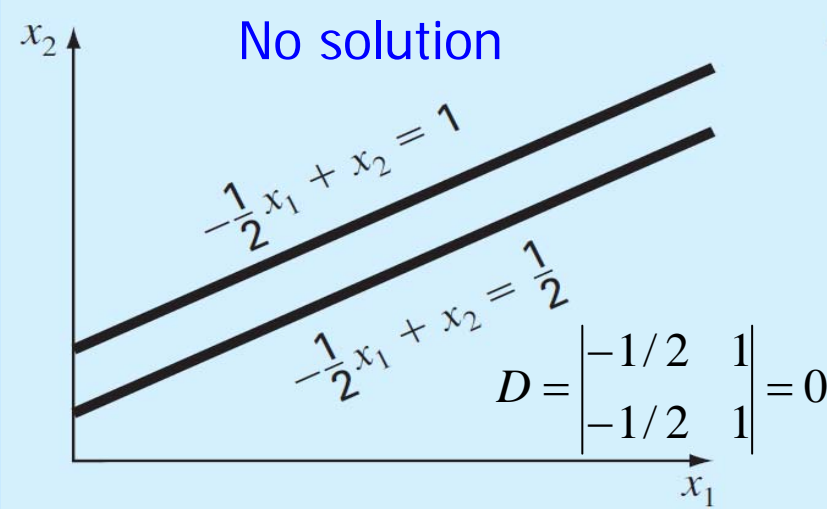
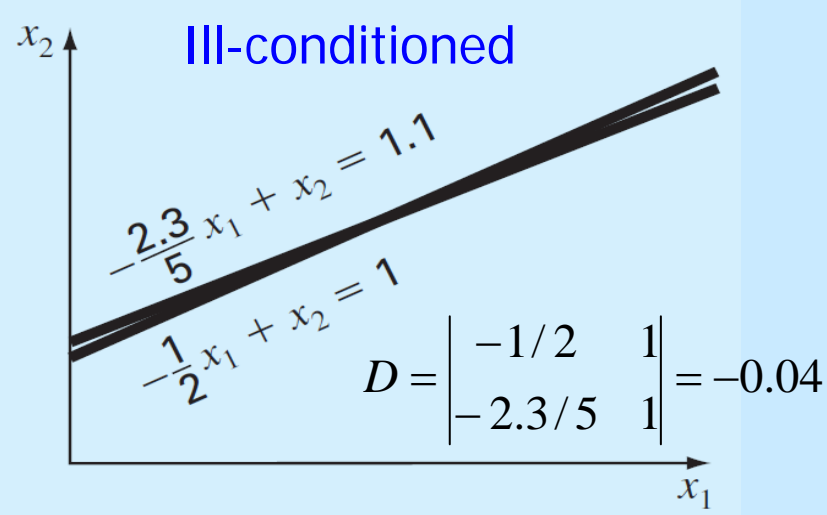
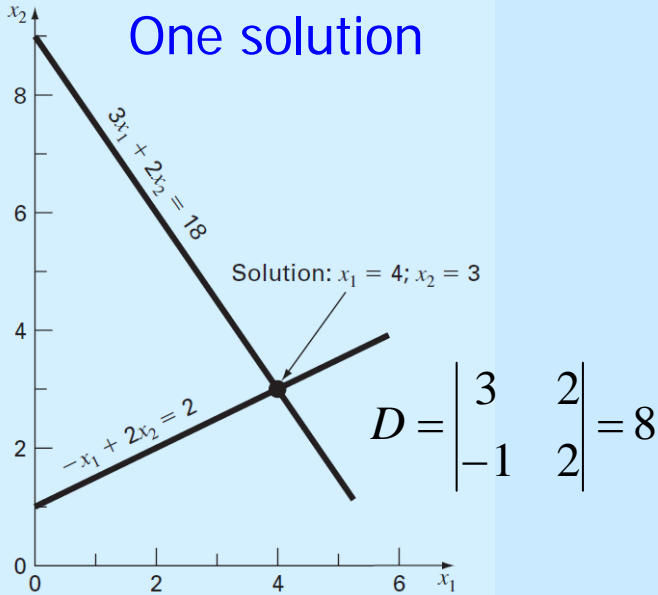
Ill-conditioned system where the slopes are so close that the point of intersection is difficult to detect visually

Determinants

$$D = |A|$$

1×1	$ a_{11} = a_{11}$
2×2	$\begin{vmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \end{vmatrix} = a_{11}a_{22} - a_{12}a_{21}$
3×3	$\begin{vmatrix} a_{11} & a_{12} & a_{13} \\ a_{21} & a_{22} & a_{23} \\ a_{31} & a_{32} & a_{33} \end{vmatrix} = a_{11} \begin{vmatrix} a_{22} & a_{23} \\ a_{32} & a_{33} \end{vmatrix} - a_{12} \begin{vmatrix} a_{21} & a_{23} \\ a_{31} & a_{33} \end{vmatrix} + a_{13} \begin{vmatrix} a_{21} & a_{22} \\ a_{31} & a_{32} \end{vmatrix}$

Determinants in linear equations



Cramer's Rule

- Each unknown in a system of linear algebraic equations may be expressed as a fraction of two determinants

$$x_1 = \frac{\begin{vmatrix} b_1 & a_{12} & a_{13} \\ b_2 & a_{22} & a_{23} \\ b_3 & a_{32} & a_{33} \end{vmatrix}}{D} \quad \begin{bmatrix} a_{11} & a_{12} & a_{13} \\ a_{21} & a_{22} & a_{23} \\ a_{31} & a_{32} & a_{33} \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} b_1 \\ b_2 \\ b_3 \end{bmatrix}$$

$$A = [0.3 \ 0.52 \ 1; \ 0.5 \ 1 \ 1.9; \ 0.1 \ 0.3 \ 0.5];$$

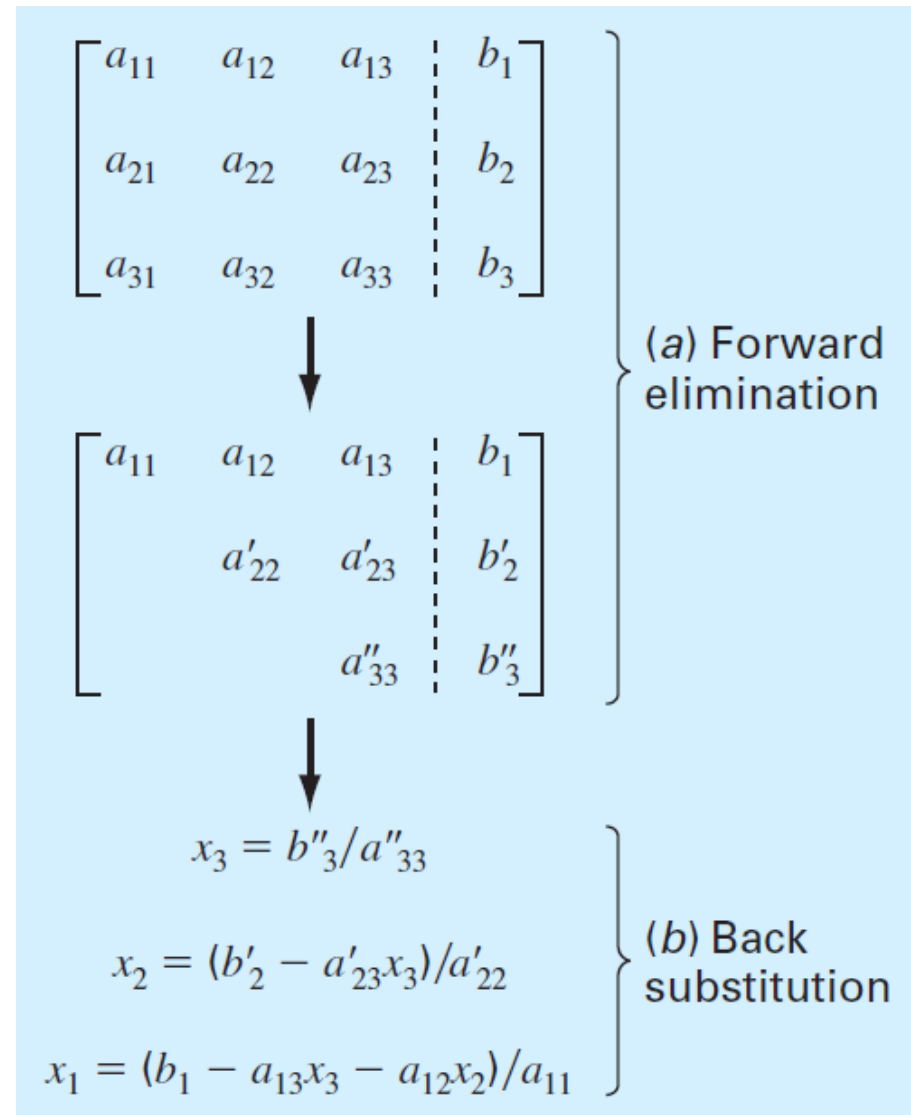
$$D = \det(A);$$

$$A(:,1) = [-0.01; \ 0.67; \ -0.44];$$

$$x_1 = \det(A)/D;$$

Naive Gauss elimination

- A sequential process of removing unknowns from equations
- 'Naive' means the process does not check for division-by-zero



Forward elimination of unknown

$$a_{11}x_1 + a_{12}x_2 + a_{13}x_3 + \dots + a_{1n}x_n = b_1$$

$$a_{21}x_1 + a_{22}x_2 + a_{23}x_3 + \dots + a_{2n}x_n = b_2$$

⋮

$$a_{n1}x_1 + a_{n2}x_2 + a_{n3}x_3 + \dots + a_{nn}x_n = b_n$$

multiplied by a_{21}/a_{11}

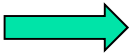
$$a_{21}x_1 + \frac{a_{21}}{a_{11}}a_{12}x_2 + \frac{a_{21}}{a_{11}}a_{13}x_3 + \dots + \frac{a_{21}}{a_{11}}a_{1n}x_n = \frac{a_{21}}{a_{11}}b_1$$

subtracted from
2nd equation

$$\left(a_{22} - \frac{a_{21}}{a_{11}}a_{12}\right)x_2 + \dots + \left(a_{2n} - \frac{a_{21}}{a_{11}}a_{1n}\right)x_n = b_2 - \frac{a_{21}}{a_{11}}b_1$$

$$a'_{22}x_2 + \dots + a'_{2n}x_n = b'_2$$

continuing n-2
eliminations



$$a_{11}x_1 + a_{12}x_2 + a_{13}x_3 + \dots + a_{1n}x_n = b_1$$

$$a'_{22}x_2 + a'_{23}x_3 + \dots + a'_{2n}x_n = b'_2$$

$$a''_{33}x_3 + \dots + a''_{3n}x_n = b''_3$$

⋮

$$a^{(n-1)}_{nn}x_n = b^{(n-1)}_n$$

backward substitution

$$a_{11}x_1 + a_{12}x_2 + a_{13}x_3 + \cdots + a_{1n}x_n = b_1$$

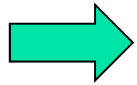
$$a'_{22}x_2 + a'_{23}x_3 + \cdots + a'_{2n}x_n = b'_2$$

$$a''_{33}x_3 + \cdots + a''_{3n}x_n = b''_3$$

\cdots

\vdots

$$a_{nn}^{(n-1)}x_n = b_n^{(n-1)}$$



$$x_n = \frac{b_n^{(n-1)}}{a_{nn}^{(n-1)}}$$

$$x_i = \frac{b_i^{(i-1)} - \sum_{j=i+1}^n a_{ij}^{(i-1)}x_j}{a_{ii}^{(i-1)}}$$

for $i = n - 1, n - 2, \dots, 1$

Example of Gauss elimination

Forward elimination

$$\begin{array}{rcl}
 3x_1 - 0.1x_2 - 0.2x_3 & = & 7.85 \\
 0.1x_1 + 7x_2 - 0.3x_3 & = & -19.3 \\
 0.3x_1 - 0.2x_2 + 10x_3 & = & 71.4
 \end{array}
 \quad
 \begin{array}{l}
 f_{21}=0.1/3 \\
 f_{31}=0.3/3
 \end{array}$$

$$\begin{array}{rcl}
 3x_1 - & 0.1x_2 - & 0.2x_3 = 7.85 \\
 & 7.00333x_2 - 0.293333x_3 & = -19.5617 \\
 & -0.190000x_2 + 10.0200x_3 & = 70.6150
 \end{array}$$

$$\begin{array}{rcl}
 3x_1 - & 0.1x_2 - & 0.2x_3 = 7.85 \\
 & 7.00333x_2 - 0.293333x_3 & = -19.5617 \\
 & & 10.0120x_3 = 70.0843
 \end{array}
 \quad
 \begin{array}{l}
 f_{32}=-0.19/7.00333
 \end{array}$$

Backward substitution

$$x_3 = \frac{70.0843}{10.0120} = 7.00003 \quad x_2 = \frac{-19.5617 + 0.293333(7.00003)}{7.00333} = -2.50000$$

$$x_1 = \frac{7.85 + 0.1(-2.50000) + 0.2(7.00003)}{3} = 3.00000$$

M-file to implement naive Gauss elimination

```
function x = GaussNaive(A,b)
[m,n] = size(A);
if m~=n, error('Matrix A must be square'); end
nb = n+1;
Aug = [A b];
% forward elimination
for k=1:n-1
    for i=k+1:n
        factor=Aug(i,k)/Aug(k,k);
        Aug(i,k:nb)=Aug(i,k:nb)-factor*Aug(k,k:nb);
    end
end
end
```

GaussNaive M-file (cont.)

`% back substitution`

`x = zeros(n,1);`

`x(n) = Aug(n,nb)/Aug(n,n);`

`for i = n-1:-1:1`

`x(i) = (Aug(i,nb)-Aug(i,i+1:n)*x(i+1:n))/Aug(i,i);`

`end`

Program efficiency

- Execution time depends on the amount of floating-point operations (flops).

$$\sum_{i=1}^m 1 = 1 + 1 + 1 + \dots + 1 = m \qquad \sum_{i=k}^m 1 = m - k + 1$$

$$\sum_{i=1}^m i = 1 + 2 + 3 + \dots + m = \frac{m(m+1)}{2} = \frac{m^2}{2} + O(m)$$

$$\sum_{i=1}^m i^2 = 1^2 + 2^2 + 3^2 + \dots + m^2 = \frac{m(m+1)(2m+1)}{6} = \frac{m^3}{3} + O(m^2)$$

Program efficiency of Gauss elimination

- Forward elimination

```

for k=1:n-1
  for i=k+1:n
    factor=Aug(i,k)/Aug(k,k);
    Aug(i,k:nb)=Aug(i,k:nb)-factor*Aug(k,k:nb);
  end
end
end

```

Outer Loop k	Inner Loop i	Addition/Subtraction Flops	Multiplication/Division Flops
1	2, n	$(n-1)(n)$	$(n-1)(n+1)$
2	3, n	$(n-2)(n-1)$	$(n-2)(n)$
\vdots	\vdots		
k	$k+1, n$	$(n-k)(n+1-k)$	$(n-k)(n+2-k)$
\vdots	\vdots		
$n-1$	n, n	$(1)(2)$	$(1)(3)$

Program efficiency of Gauss elimination (cont.)

- Total addition/subtraction flops of forward elimination

$$\sum_{k=1}^{n-1} (n-k)(n+1-k) = \sum_{k=1}^{n-1} [n(n+1) - k(2n+1) + k^2]$$

$$n(n+1) \sum_{k=1}^{n-1} 1 - (2n+1) \sum_{k=1}^{n-1} k + \sum_{k=1}^{n-1} k^2$$

$$\Rightarrow [n^3 + O(n^2)] - [n^3 + O(n^2)] + \left[\frac{1}{3}n^3 + O(n^2) \right] = \frac{n^3}{3} + O(n^2)$$

- Similar analysis for multiplication/division flops

$$[n^3 + O(n^2)] - [n^3 + O(n)] + \left[\frac{1}{3}n^3 + O(n^2) \right] = \frac{n^3}{3} + O(n^2)$$

- Total $\frac{2n^3}{3} + O(n^2)$

Program efficiency of Gauss elimination (cont.)

$$\underbrace{\frac{2n^3}{3} + O(n^2)}_{\text{Forward elimination}} + \underbrace{n^2 + O(n)}_{\text{Back substitution}} \xrightarrow{\text{as } n \text{ increases}} \frac{2n^3}{3} + O(n^2)$$

TABLE 9.1 Number of flops for naive Gauss elimination.

n	Elimination	Back Substitution	Total Flops	$2n^3/3$	Percent Due to Elimination
10	705	100	805	667	87.58%
100	671550	10000	681550	666667	98.53%
1000	6.67×10^8	1×10^6	6.68×10^8	6.67×10^8	99.85%

Problems arise with naive Gauss elimination

- If a coefficient along the diagonal is 0 (division by 0) or close to 0 (round-off error)

$$\begin{aligned} 2x_2 + 3x_3 &= 8 \\ 4x_1 + 6x_2 + 7x_3 &= -3 \\ 2x_1 - 3x_2 + 6x_3 &= 5 \end{aligned}$$

$$\begin{aligned} 0.0003x_1 + 3.0000x_2 &= 2.0001 \\ 1.0000x_1 + 1.0000x_2 &= 1.0000 \end{aligned}$$

↓ Gauss elimination

$$\begin{aligned} -9999x_2 &= -6666 \\ x_1 &= \frac{2.0001 - 3(2/3)}{0.0003} \end{aligned}$$

Significant Figures	x_2	x_1	Absolute Value of Percent Relative Error for x_1
3	0.667	-3.33	1099
4	0.6667	0.0000	100
5	0.66667	0.30000	10
6	0.666667	0.330000	1
7	0.6666667	0.3330000	0.1

Pivoting

- **Partial pivoting** : Determine the coefficient with the largest absolute value in the column below the pivot element. The rows can then be switched so that the largest element is the pivot element.
- **Complete pivoting** : If the rows to the right of the pivot element are also checked and columns switched.

Example by partial pivoting

$$0.0003x_1 + 3.0000x_2 = 2.0001$$

$$1.0000x_1 + 1.0000x_2 = 1.0000$$

↓ Partial pivoting

$$1.0000x_1 + 1.0000x_2 = 1.0000$$

$$0.0003x_1 + 3.0000x_2 = 2.0001$$

↓ Gauss elimination

$$x_2 = 2/3$$

$$x_1 = \frac{1 - (2/3)}{1}$$

Significant Figures	x_2	x_1	Absolute Value of Percent Relative Error for x_1
3	0.667	0.333	0.1
4	0.6667	0.3333	0.01
5	0.66667	0.33333	0.001
6	0.666667	0.333333	0.0001
7	0.6666667	0.3333333	0.0000

M-file to implement partial pivoting

```
function x = GaussPivot(A,b)
[m,n]=size(A);
if m~=n, error('Matrix A must be square'); end
nb=n+1;
Aug=[A b];
```

```
% forward elimination
```

```
for k = 1:n-1
    % partial pivoting
    [big,i]=max(abs(Aug(k:n,k)));
    ipr=i+k-1;
    if ipr~=k % rows exchange
        Aug([k,ipr],:)=Aug([ipr,k],:);
    end
end
```

Partial pivoting M-file (cont.)

```
for i = k+1:n
    factor=Aug(i,k)/Aug(k,k);
    Aug(i,k:nb)=Aug(i,k:nb)-factor*Aug(k,k:nb);
end
end
```

% back substitution

```
x=zeros(n,1);
x(n)=Aug(n,nb)/Aug(n,n);
for i = n-1:-1:1
    x(i)=(Aug(i,nb)-Aug(i,i+1:n)*x(i+1:n))/Aug(i,i);
end
```


M-file for tridiagonal system solver

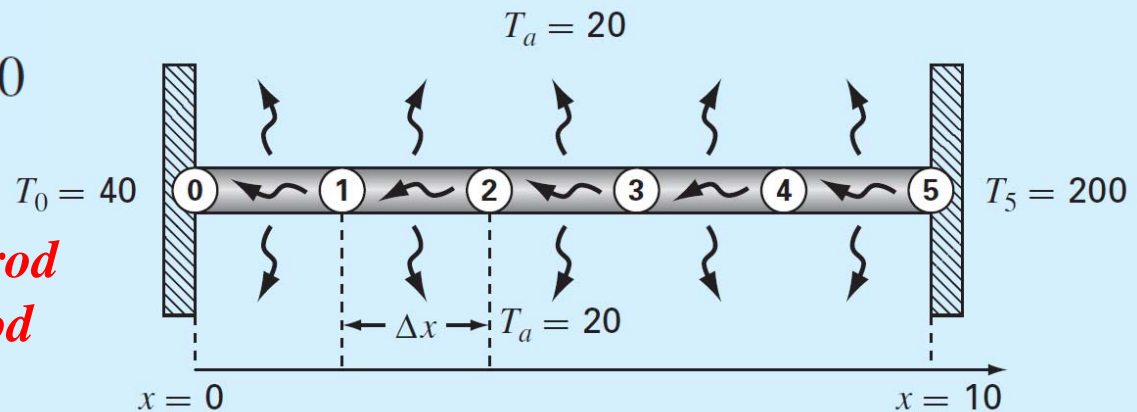
```
function x = Tridiag(e,f,g,r)
% e, f, g = subdiagonal, diagonal & superdiagonal vectors
n=length(f);
% forward elimination
for k=2:n
    factor = e(k)/f(k-1);
    f(k) = f(k) - factor*g(k-1);
    r(k) = r(k) - factor*r(k-1);
end
% back substitution
x(n) = r(n)/f(n);
for k = n-1:-1:1
    x(k) = (r(k)-g(k)*x(k+1))/f(k);
end
```

A heated rod

- Steady-state, differential equation based on heat conservation

$$\frac{d^2T}{dx^2} + h'(T_a - T) = 0$$

Heat flows through the rod as well as between the rod and the surrounding air



- Finite-difference approximation

$$\frac{T_{i+1} - 2T_i + T_{i-1}}{\Delta x^2} + h'(T_a - T_i) = 0$$

A heated rod (cont.)

Given $h' = 0.01$, $T_a = 20$, $T(0) = 40$, $T(10) = 200$, get a solution

$$\frac{T_{i+1} - 2T_i + T_{i-1}}{\Delta x^2} + h'(T_a - T_i) = 0$$

Using $\Delta x = 2$

$$-T_{i-1} + 2.04T_i - T_{i+1} = 0.8$$

$$-T_0 + 2.04T_1 - T_2 = 0.8$$

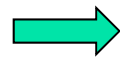
$$-T_1 + 2.04T_2 - T_3 = 0.8$$

$$-T_2 + 2.04T_3 - T_4 = 0.8$$

$$-T_3 + 2.04T_4 - T_5 = 0.8$$

$$T_0 = 40$$

$$T_5 = 200$$



$$\begin{bmatrix} 2.04 & -1 & 0 & 0 \\ -1 & 2.04 & -1 & 0 \\ 0 & -1 & 2.04 & -1 \\ 0 & 0 & -1 & 2.04 \end{bmatrix} \begin{Bmatrix} T_1 \\ T_2 \\ T_3 \\ T_4 \end{Bmatrix} = \begin{Bmatrix} 40.8 \\ 0.8 \\ 0.8 \\ 200.8 \end{Bmatrix}$$

A heated rod (cont.)

`% Using left division`

```
A=[2.04 -1 0 0; -1 2.04 -1 0; 0 -1 2.04 -1; 0 0 -1 2.04];
```

```
b=[40.8 0.8 0.8 200.8]';
```

```
T=(A\b)';
```

`% Using tridiagonal system solver`

```
e=[0 -1 -1 -1];
```

```
f=[2.04 2.04 2.04 2.04];
```

```
g=[-1 -1 -1 0];
```

```
r=[40.8 0.8 0.8 200.8];
```

```
T=Tridiag(e,f,g,r);
```

Reference

- Steven C. Chapra "Applied Numerical Methods with MATLAB", 3rd ed., McGraw Hill, 2012.